

Lecture 5: Spatial Algorithms

GEOG 419: Advanced GIS

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Spatial Analysis Algorithms

- Basis of much of GIS analysis today
- Manipulation of map coordinates
- Based on Euclidean coordinate geometry
- <http://astronomy.swin.edu.au/~pbourke/geometry/>

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A matter of analytical cartography

- Theoretical and mathematical background behind cartography
- Seeks to find how geographic properties of space can be used in analysis, modeling, and prediction
- Analytical Cartography consists of the basic mathematical algorithms and principles of cartography that survive independently of a particular technology

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AC Algorithms

- **Algorithm** – special method for solving a problem stated as a formula or a set of sequential instructions
- **Church's Theorem** – if a problem can be stated as a series of sequential instructions, then it can be automated
- Cartographic transformational algorithms are the nuts and bolts from which GIS are constructed

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Matrices

- If you are going to understand AC algorithms, you should understand something about matrix algebra
- **Matrix:** a set of numbers or symbols arranged in a square or rectangular array of “m” rows and “n” columns. The arrangement is such that certain defined mathematical operations can be performed in a systematic and efficient way

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Linear equations and matrices

Given a set of linear equations

$$a_1x_1 + a_1x_2 + a_1x_3 = c_1$$

$$a_2x_1 + a_2x_2 + a_2x_3 = c_2$$

$$a_3x_1 + a_3x_2 + a_3x_3 = c_3$$

$$x + y - z = -8$$

$$2x - y + z = -4$$

$$-x + 2y + 2z = 21$$

We can define them in matrix form

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix}$$

And further define them in matrix notation

$$AX = C$$

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- So, if we have a system of linear equations

$$AX = C$$

- We can algebraically reformat the equation by pre-multiplying both sides by the identity matrix

$$\begin{aligned} AX &= C \\ A^{-1}X &= A^{-1}C \\ IX &= A^{-1}C \\ X &= A^{-1}C \end{aligned}$$

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Solving simultaneous equations

- We can solve the following equation simultaneously through based algebraic manipulation

$$x + 5y = -8$$

$$-x - 2y = -1$$

solving for y, we reduce to

$$x + 5y + 8 = -x - 2y + 1$$

now add the two equations

$$x + 5y + 8$$

$$\underline{-x - 2y + 1}$$

$$3y = -9$$

$$y = -3$$

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Solving simultaneous equations with matrices

- Or, we can use matrices

$$x + 5y = -8$$

$$-x - 2y = -1$$

$$\underbrace{\begin{bmatrix} 1 & 5 \\ -1 & -2 \end{bmatrix}}_A \underbrace{\begin{bmatrix} x \\ y \end{bmatrix}}_X = \underbrace{\begin{bmatrix} -8 \\ -1 \end{bmatrix}}_C$$

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More complicated formulas

$$x + 5y = -8$$

$$A = \begin{pmatrix} 1 & 5 \\ -1 & -2 \end{pmatrix} \quad C = \begin{pmatrix} -8 \\ -1 \end{pmatrix}$$

$$-x - 2y = -1$$

$$(A^T A)^{-1} A^T C = \begin{pmatrix} 7 \\ -3 \end{pmatrix}$$

$$x + y - z = -8$$

$$A = \begin{pmatrix} 1 & 1 & -1 \\ 3 & -1 & 1 \\ -1 & 2 & 2 \end{pmatrix} \quad C = \begin{pmatrix} -8 \\ -4 \\ 21 \end{pmatrix}$$

$$2x - y + z = -4$$

$$-x + 2y + 2z = 21$$

$$(A^T A)^{-1} A^T C = \begin{pmatrix} -3 \\ 2 \\ 7 \end{pmatrix}$$

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Transformational View of Cartography

- Types of data/types of maps
- Map scale
- Dimensional
- Symbolization
- Generalization
- Data model

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Transformations

- Goal is to express a transformation as an explicit math operation so that $0 \rightarrow 1$ in a fully described way and an inverse transformation $1 \rightarrow 2 = 0$
- Invertible transformations
 - Special subset, allows for prediction of error, spatial modeling
- Point-to-point transformations – very central, more than any other
- Can have multi-step transformations

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Dimensional Transformations

- Coordinate transformations
 - Projections
- Geometric transformations
 - Measurements from coordinates
- Affine transformations
 - Rotation, translation, and scaling
- Statistical space transformations

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Planar map transformations

- Distance between two points
 - Figured out 2,400 years ago by Pythagoras

$$d_{2to1} = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}$$

- Is this invertible? Only if we have three points

- Length of a line

$$length = \sum_{i=1}^{npts-1} \sqrt{(x_i - x_{i-1})^2 + (y_i - y_{i-1})^2}$$

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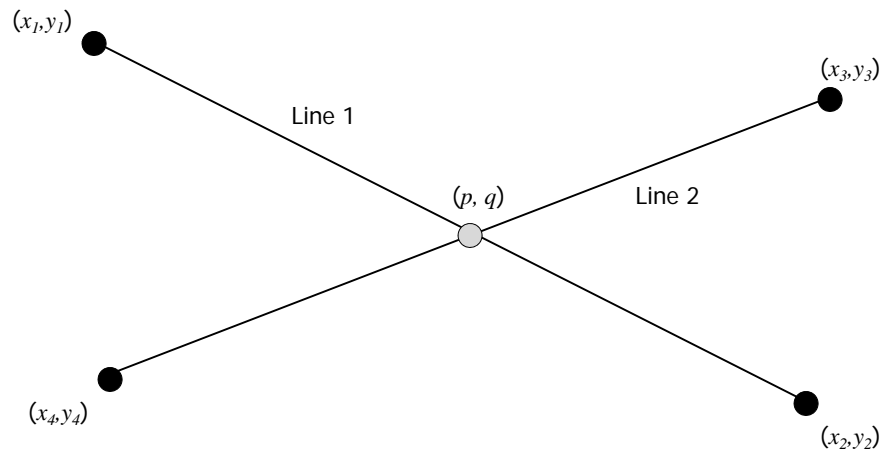
Planar map transformations II

- Weighted average point
- Cities (x,y,P) P = population

$$\bar{x} = \frac{\sum_{i=1}^{npts} P_i x_i}{\sum_{i=1}^{npts} P_i} \qquad \bar{y} = \frac{\sum_{i=1}^{npts} P_i y_i}{\sum_{i=1}^{npts} P_i}$$

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Intersection point of two lines



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Intersection point of two lines

- If (x_1, y_1) and (x_2, y_2) lie on the same line then:

$$y_1 = a_1 + b_1x_1$$

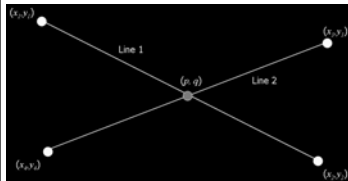
$$y_2 = a_1 + b_1x_2$$

remember $y = mx + b$ (the equation of a line)

- If (x_3, y_3) and (x_4, y_4) lie on the same line then:

$$y_3 = a_2 + b_2x_3$$

$$y_4 = a_2 + b_2x_4$$



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Intersection point of two lines

- If an intersection exists, it must lie on both lines:

$$y = a_1 + b_1x$$

$$y = a_2 + b_2x$$

- Solve for simultaneous equations:

$$y - y = a_1 - a_2 + x(b_1 - b_2)$$

- Rearrange to get:

$$a_1 - a_2 = x(b_1 - b_2)$$

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Intersection point of two lines

- Solving for x :

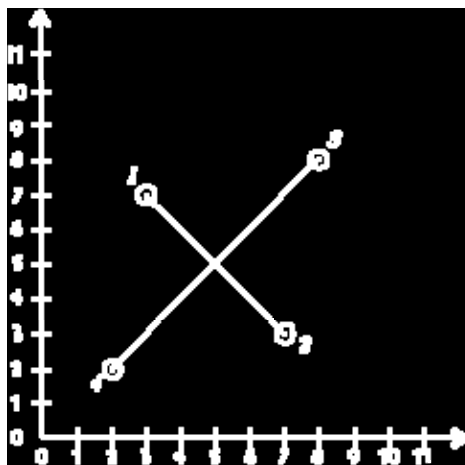
$$x = \frac{a_1 - a_2}{b_1 - b_2}$$

- And by substituting, solve for y :

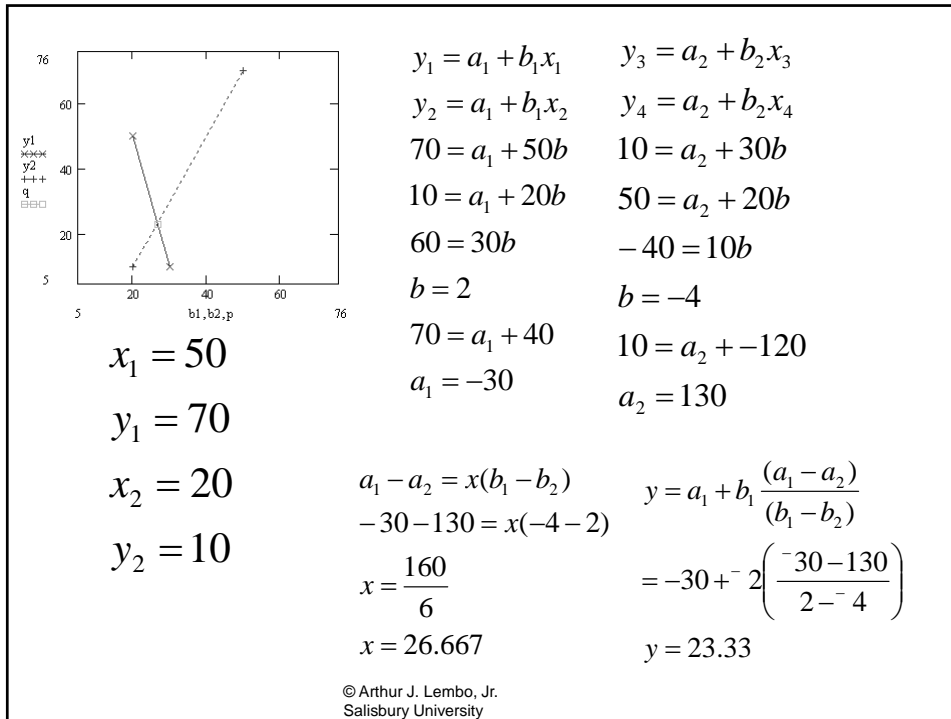
$$y = a_1 + b_1 \frac{(a_1 - a_2)}{(b_1 - b_2)}$$

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An example of line intersection



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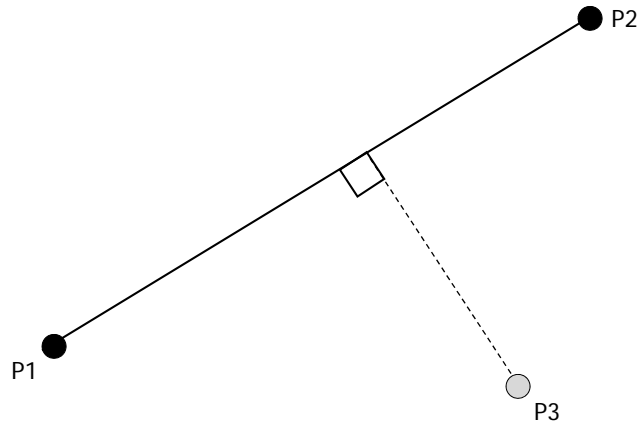


Intersection of two lines

- If the denominator above is 0, the lines are parallel
- If the denominator and the numerator above is 0, the lines are coincident
- In the computer, we have a real problem with 0
 - Actual zero almost never happens
 - Means we must check within limits of coordinate precision
- Solution is not elegant – test every combination of line segments
 - Bounding Box heuristic

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Distance between a point and a line

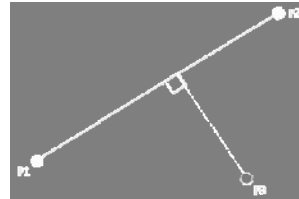


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Distance between a point and a line

- Equation for the line

$$P = P1 + u(P2 - P1)$$



- The shortest distance from P3 to P is a perpendicular line. This means the dot product of the line and the perpendicular is 0.

$$(P3 - P) \text{ dot } (P2 - P1) = 0$$

The dot product is often used to calculate the cosine of the angle between two vectors.

- Substitute for the equation of the line

$$[P3 - P1 - u(P2 - P1)] \text{ dot } (P2 - P1) = 0$$

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Distance between point and line

- Solve for u

$$u = \frac{(x_3 - x_1)(x_2 - x_1) + (y_3 - y_1)(y_2 - y_1)}{\left(\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2}\right)^2}$$

- Find the intersection point

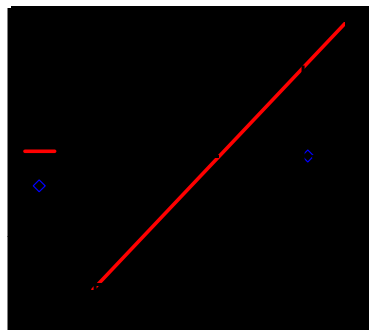
$$x = x_1 + u(x_2 - x_1)$$

$$y = y_1 + u(y_2 - y_1)$$

- Distance is length of line between P3 and intersection point

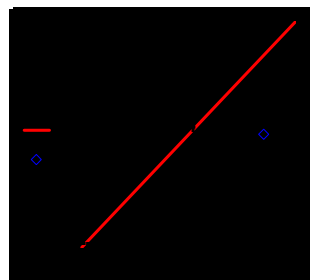
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Clockwise vs. counter clockwise



$$(ptx - x1) \cdot (y2 - y1) - (x2 - x1) \cdot (pty - y1) \neq -20$$

What if its on the line?

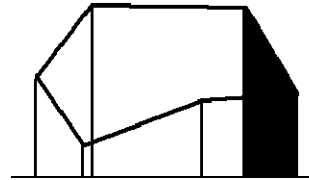
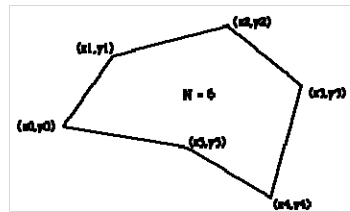


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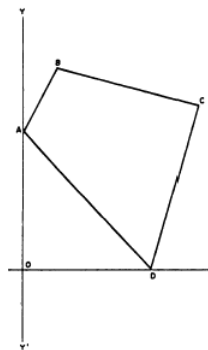
Area of a polygon

$$A = \frac{1}{2} \left| \sum_{i=1}^{npts+1} (x_i y_{i-1}) - (x_{i-1} y_i) \right|$$

- Project lines from each vertex to some outside perpendicular. Each area under the line is a triangle and a rectangle. Sum the areas as you move around the polygon. Outside areas get subtracted out



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$$\frac{1}{2} \sum_{i=0}^{N-1} (x_i y_{i+1} - x_{i+1} y_i)$$

STATION	COORDINATES	
	y	x
A	591.64	0
B	847.60	125.66
C	694.07	716.31
D	0	523.62
A	591.64	0

$$591.64 \times 125.66 = 74,345.48$$

$$847.60 \times 716.31 = 607,144.35$$

$$694.07 \times 523.62 = 363,428.93$$

$$0 \times 0 = 0$$

$$\Sigma \rightarrow 1,044,918.76$$

STATION	COORDINATES	
	y	x
A	591.64	0
B	847.60	125.66
C	694.07	716.31
D	0	523.62
A	591.64	0

$$0 \times 847.60 = 0$$

$$125.66 \times 694.07 = 87,216.84$$

$$716.31 \times 0 = 0$$

$$523.62 \times 591.64 = 309,794.53$$

$$\Sigma \rightarrow 397,011.37$$

What we have covered this semester

- Brief and fast review of GIS
 - Structure of GIS (HW/SW, file based, object based, object-relational) GIS data models (raster, vector, TIN)
- Object modeling and geodatabases
 - Geo-relational model, object oriented concepts, object behavior, benefits of geodatabases
 - Making features smart, qualities of features in a geodatabase, subtype, relationship classes
- Cartographic modeling
 - General principles in cartographic modeling, transfer of principles to Model Builder, spatial SQL
- Database design
 - Data models, entity-relationship diagrams, spatial entities in E-R diagrams, physical and logical design, design steps (model user view, define entities and relationships, transition to physical model)
 - ESRI Geodatabase structure (geodatabase, feature dataset, feature and object classes, relationship classes, rules)

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What we have covered this semester

- Vector GIS operations
 - Vector functions (scale change, buffer, clip, overlay, Thiessen polygons, Delaunay triangulation)
 - Map transformations (conformal, affine, polynomials, rubbersheeting), raster transformation (WTC example)
 - Spatial algorithms (concept of an algorithm, mathematics of analytical cartography: distance, intersection, containment)

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How you got your hands dirty

- Review of classic GIS functions for site selection
- Getting real world data into GIS (even when the data isn't very good)
 - rubbersheeting and raster transformation
- Integration of classic GIS functions in a modern computing environment (model builder)
- Creating a geodatabase (controlled environment)
- Creating a geodatabase (non controlled environment)

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What's on the written exam

- 10 definitions
- 3 short answers (lists, benefits/limitations, etc.)
- 1 computation (i.e. area, centroid, distance, intersection)
- 2 essays (conceptual ideas)

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What's on the practicum

- Hands-on work
 - Create a geodatabase
 - Digitize boundaries
 - Create a small GIS analysis

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