

3. (5 points) Define the term "neutral geometry" and specify two distinctly different models for neutral geometry. Explain how you know your two models are distinctly different.

A plane geometry is neutral if it does not include a parallel postulate or an equivalent postulate.

✓ Euclidean Geometry

✓ Hyperbolic Geometry

are two models for neutral geometry.

In Euclidean geometry we have the existence of unique parallels. In Hyperbolic geometry we do not have unique parallels - we have many parallels to a given line that pass through any point not on the given line.

4. (5 points) Prove that the following statement is a theorem in any incidence geometry that has I-1, I-2, ..., I-7 as axioms. Use exemplary proof style in your argument.

If two lines intersect, then there is exactly one plane that contains them both.

Suppose l_1 and l_2 are two lines that intersect.

l_1 and l_2 have a point R in common. By I-2

l_1 and l_2 each have at least one other point. Suppose

A is a point other than R on l_1 and B is a

point other than R on l_2 . R, A , and B are

not collinear. If they were collinear, then l_1 and l_2 would be the same line by I-1. Axiom I-4 implies

there is a unique plane π containing R, A , and B .

By I-5, l_1 and l_2 are both in that plane.

That plane must be unique because it contains R, A , and B .

So, if two lines intersect, there is exactly one plane that contains them both.