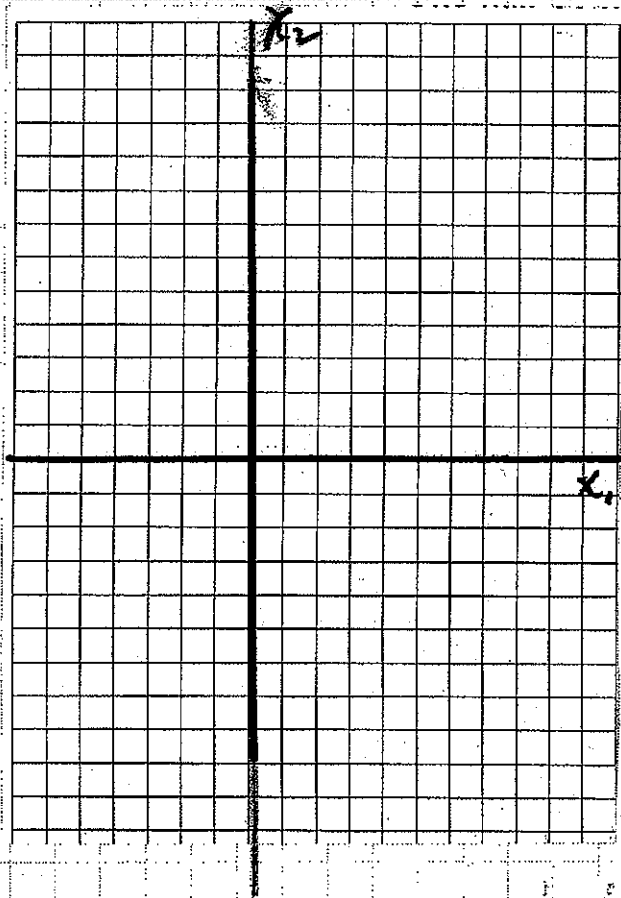


Session #5 Warm Up

1. Solve and Graph the Solution Sets

a) $-2x_1 + x_2 = 0$

b) $-2x_1 + x_2 = 3$



2. Solve and Describe the Solution Sets

a.
$$\begin{cases} x_1 - 2x_2 + 2x_3 = 0 \\ x_3 = 0 \end{cases}$$

b.
$$\begin{cases} x_1 - 2x_2 + 2x_3 = 3 \\ x_3 = 3 \end{cases}$$

Session # 5

Consider the matrix $A = \begin{bmatrix} 2 & -1 & 4 \\ 1 & -\frac{1}{2} & 3 \\ 4 & -2 & 10 \end{bmatrix}$ and the vector $\bar{0} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$. Find those vectors $\bar{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ such that $A\bar{x} = \bar{0}$. Provide a geometric interpretation for the solution set for the equation $A\bar{x} = \bar{0}$.

Linear systems that can be written in the form $A\bar{x} = \bar{0}$ are called homogeneous systems. Such systems must have at least one solution since $A\bar{0} = \bar{0}$. That zero solution is called the trivial solution. We are interested in nontrivial solutions.

Find all solutions for $A\bar{x} = \bar{b}$ where $A = \begin{bmatrix} 2 & -1 & 4 \\ 1 & -\frac{1}{2} & 3 \\ 4 & -2 & 10 \end{bmatrix}$ and $\bar{b} = \begin{bmatrix} 6 \\ 3 \\ 12 \end{bmatrix}$. Provide a geometric description of that solution set.

1. Solve:
$$\begin{cases} x_1 - 2x_2 + 2x_3 = 3 \\ x_3 = 3 \end{cases}$$

2. Solve:
$$x_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} -2 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \end{bmatrix}$$

3. Solve:
$$\begin{bmatrix} 1 & -2 & 2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 3 \end{bmatrix}$$

4. Can $\begin{bmatrix} 3 \\ 3 \end{bmatrix}$ be written as a linear combination of $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$, $\begin{bmatrix} -2 \\ 0 \end{bmatrix}$, and $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$?

5. Is $\begin{bmatrix} 3 \\ 3 \end{bmatrix}$ in $\text{span} \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \end{bmatrix} \right\}$?

Show, by a geometric construction, that the vector \vec{b} can be written as a l.c. of $\vec{v}_1, \vec{v}_2,$ and \vec{v}_3 .
Is that representation unique?

