

# Assignment #10

4.3/420 We seek a basis for  $H = \text{span} \{ \vec{v}_1, \vec{v}_2, \vec{v}_3 \}$   
 where  $\vec{v}_1 - 3\vec{v}_2 + 5\vec{v}_3 = \vec{0}$

Of course  $\vec{v}_1 = 3\vec{v}_2 - 5\vec{v}_3$ . So, if  $\vec{x} = x_1\vec{v}_1 + x_2\vec{v}_2 + x_3\vec{v}_3$   
 is any element of  $H$ , then  $\vec{x} = (3x_1\vec{v}_2 - 5x_1\vec{v}_3) + x_2\vec{v}_2 + x_3\vec{v}_3$   
 $= (3x_1 + x_2)\vec{v}_2 + (-5x_1 + x_3)\vec{v}_3$ .

So,  $\vec{x}$  is in  $\text{span} \{ \vec{v}_2, \vec{v}_3 \}$ . Hence  $H = \text{span} \{ \vec{v}_2, \vec{v}_3 \}$ .  
 We can also see that  $\{ \vec{v}_2, \vec{v}_3 \}$  is a linearly independent  
 set. Consequently  $\{ \vec{v}_2, \vec{v}_3 \}$  is a basis for  $H$ .

4.3/402 a) False. The set must also span  $H$

b) True. Theorem 5.8

c) True. Page 242

d) False Page 242

e) False Page 242

4.3/420  $\{ \sin t, \sin 2t \}$  is a basis for  $\text{span} \{ \sin t, \sin 2t, \sin t \cos t \}$

because  $\sin 2t = 2 \sin t \cos t$ .

4.3/434  $\vec{p}_1(t) = 1+t$ ,  $\vec{p}_2(t) = 1-t$ , and  $\vec{p}_3(t) = 2$ .  
 A linear dependence relation on  $\vec{p}_1, \vec{p}_2, \vec{p}_3$   
 is

$$1 \cdot \vec{p}_1(t) + 1 \cdot \vec{p}_2(t) - 1 \cdot \vec{p}_3(t) = \vec{0}$$

$\{ \vec{p}_1, \vec{p}_2 \}$  is a basis for  $\text{span} \{ \vec{p}_1, \vec{p}_2, \vec{p}_3 \}$

4.4/44  $P_B[\vec{x}]_B = \vec{x} \Rightarrow \begin{bmatrix} -1 & 3 & 4 \\ 2 & -5 & -7 \\ 0 & 2 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ -5 \end{bmatrix}$

4.4  
#8

$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & -1 \\ 3 & 8 & 2 \end{bmatrix} [\bar{x}]_B = \begin{bmatrix} 3 \\ -5 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 1 & : & 3 \\ 0 & 1 & -1 & : & -5 \\ 3 & 8 & 2 & : & 4 \end{bmatrix} \text{ rref } \sim \begin{bmatrix} 1 & 0 & 0 & -2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 5 \end{bmatrix}$$

$$\Rightarrow [\bar{x}]_B = \begin{bmatrix} -2 \\ 0 \\ 5 \end{bmatrix}$$

4.4  
#12

$$P_B = \begin{bmatrix} 4 & 6 \\ 5 & 7 \end{bmatrix} \Rightarrow P_B^{-1} = \begin{bmatrix} -7 & 3 \\ 2 & -2 \end{bmatrix}$$

$$P_B [\bar{x}]_B = \bar{x} \Rightarrow [\bar{x}]_B = P_B^{-1} \begin{bmatrix} 2 \\ 0 \end{bmatrix} \Rightarrow [\bar{x}]_B = \begin{bmatrix} -7 \\ 5 \end{bmatrix}$$

4.4  
#14

Give  $B = \{1-t^2, t-t^2, 2-2t+t^2\}$  is a basis for  $\mathbb{P}_2$ .  
we seek  $[\bar{p}]_B$  where  $\bar{p}(t) = 3+t-6t^2$ .

that is, we seek  $x_1, x_2, x_3$  such that

$$\begin{aligned} x_1(1-t^2) + x_2(t-t^2) + x_3(2-2t+t^2) &= 3+t-6t^2 \\ (x_1 + 2x_3) + (x_2 - 2x_3)t + (-x_1 - x_2 + x_3)t^2 &= 3+t-6t^2 \end{aligned}$$

So,

$$\begin{cases} x_1 + 2x_3 = 3 \\ x_2 - 2x_3 = 1 \\ -x_1 - x_2 + x_3 = -6 \end{cases} \Leftrightarrow \begin{bmatrix} 1 & 0 & 2 & 3 \\ 0 & 1 & -2 & 1 \\ -1 & -1 & 1 & -6 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 7 \\ 0 & 1 & 0 & -3 \\ 0 & 0 & 1 & -2 \end{bmatrix}$$

$$\Rightarrow [\bar{p}]_B = \begin{bmatrix} 7 \\ -3 \\ -2 \end{bmatrix}$$

4.4 #32  $\bar{p}_1(t) = 1+t^2 \leftrightarrow \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}; \bar{p}_2(t) = 2-t+3t^2 \leftrightarrow \begin{bmatrix} 2 \\ -1 \\ 3 \end{bmatrix}; \bar{p}_3(t) = 1+2t-4t^2 \leftrightarrow \begin{bmatrix} 1 \\ 2 \\ -4 \end{bmatrix}$

a)  $\begin{bmatrix} 1 & 2 & 1 \\ 0 & -1 & 3 \\ 1 & 2 & -4 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow \{\bar{p}_1, \bar{p}_2, \bar{p}_3\}$  is a basis for  $\mathbb{P}_2$ . (IMT)

b)  $P_B [\bar{q}]_B = \bar{q} \Rightarrow \bar{q}(t) = 3\bar{p}_1(t) + 1\bar{p}_2(t) + 2\bar{p}_3(t)$   
 $\Rightarrow \bar{q}(t) = 1+3t-8t^2 \leftrightarrow \begin{bmatrix} 1 \\ 3 \\ -8 \end{bmatrix}$