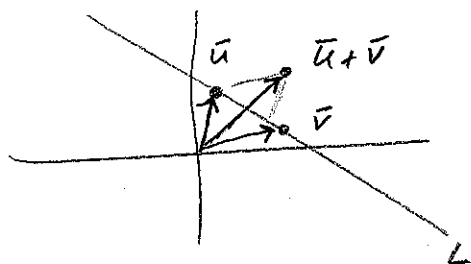


Assignment 9

①

4.1
#4



Consider line L in \mathbb{R}^2

$\bar{u}, \bar{v} \in L$ but $\bar{u} + \bar{v} \notin L$.

So, L is not closed under addition.

4.1
#8

The set of all polynomials in \mathbb{P}_n such that $\bar{p}(0) = 0$ is a subspace of \mathbb{P}_n .

Take $\bar{p}, \bar{q} \in \mathbb{P}_n$, $(\bar{p} + \bar{q})(0) = \bar{p}(0) + \bar{q}(0) = 0 + 0 = 0$

So $\bar{p} + \bar{q}$ is in the set $H = \{ \bar{p} \in \mathbb{P}_n : \bar{p}(0) = 0 \}$

Take $\bar{p} \in \mathbb{P}_n$ and $c \in \mathbb{R}$, $(c\bar{p})(0) = c(\bar{p}(0)) = c \cdot 0 = 0$.

So, $c\bar{p} \in H$. Hence, H is closed under addition and scalar multiplication.

So, by the definition of subspace H is a subspace of \mathbb{P}_n .

4.1
#10

$$H = \left\{ \bar{x} : \bar{x} = \begin{bmatrix} 2t \\ 0 \\ -t \end{bmatrix} \text{ for } t \in \mathbb{R} \right\}$$

$H = \text{span} \left\{ \begin{bmatrix} 2 \\ 0 \\ -1 \end{bmatrix} \right\}$. So, by Theorem 4.1 (4.1) H is a subspace of \mathbb{R}^3 .

4.1
#14

To see if $\bar{w} = \begin{bmatrix} 8 \\ 4 \\ 7 \end{bmatrix}$ is in the subspace $\text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ 2 \\ 6 \end{bmatrix} \right\}$ we solve the system with augmented matrix M below

$$M = \begin{bmatrix} 1 & 2 & 4 & 8 \\ 0 & 1 & 2 & 4 \\ -1 & 3 & 6 & 7 \end{bmatrix} \xrightarrow{\text{rref}} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}. \text{ Since the system}$$

has no solution $\bar{w} \notin \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ 2 \\ 6 \end{bmatrix} \right\}$

(2)

$$4.1 \left. \begin{array}{l} \#16 \end{array} \right\} W = \left\{ \bar{x} : \bar{x} = \begin{bmatrix} -a+1 \\ a-6b \\ 2b+a \end{bmatrix} \right\} = \left\{ \bar{x} : \bar{x} = a \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} + b \begin{bmatrix} 0 \\ -6 \\ 2 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right\}$$

So, $\bar{0} \notin W$. Hence, W is not a vector space.

$$4.1 \left. \begin{array}{l} \#18 \end{array} \right\} W = \left\{ \bar{x} : \bar{x} = \begin{bmatrix} 4a+3b \\ 0 \\ a+b+c \\ c-2a \end{bmatrix}, a, b, c \in \mathbb{R} \right\}$$

$$= \left\{ \bar{x} : \bar{x} = a \begin{bmatrix} 4 \\ 0 \\ 1 \\ -2 \end{bmatrix} + b \begin{bmatrix} 3 \\ 0 \\ 1 \\ 0 \end{bmatrix} + c \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}, a, b, c \in \mathbb{R} \right\}$$

$$= \text{span} \left\{ \begin{bmatrix} 4 \\ 0 \\ 1 \\ -2 \end{bmatrix}, \begin{bmatrix} 3 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix} \right\}$$

So, W is a subspace of \mathbb{R}^4 by Theorem 1 (4.1)

4.1 $\left. \begin{array}{l} \#20 \end{array} \right\}$ a) To show that $C[a, b]$ is a subspace we must show

- \bar{f} defined by $f(t) = 0$ for all $t \in [a, b]$

- For any functions $\bar{g}, \bar{h} \in C[a, b]$, $\bar{g} + \bar{h} \in C[a, b]$

- For any $\bar{g} \in C[a, b]$ and $c \in \mathbb{R}$, $c\bar{g} \in C[a, b]$

b) We will show $H = \{ \bar{f} \in C[a, b] : f(a) = f(b) \}$ is a subspace of $C[a, b]$.

✓ $\bar{h}(t) = 0$, the zero function is in H because $h(a) = h(b) = 0$.

✓ Suppose $\bar{f}, \bar{g} \in H$. Then $f(a) = f(b)$ and $g(a) = g(b)$.

$$(\bar{f} + \bar{g})(a) = f(a) + g(a) = f(b) + g(b) = (f + g)(b)$$

✓ Suppose $\bar{f} \in H$ and $c \in \mathbb{R}$. Then $(c\bar{f})(a) = c(f(a)) = c(f(b)) = (c\bar{f})(b)$

So, H is a subspace of $C[a, b]$.

- 4.1
#214
- a) True - Definition of vector space
 - b) True - See p. 217 (above blue box)
 - c) True - See p. 220 (above Example 6)
 - d) False - See Example 8
 - e) False - \bar{u} and \bar{v} must be arbitrary elements in H

- 4.1
#220
- a) Axiom 3
 - b) Axiom 5
 - c) Axiom 4

- 4.1
#28
- a) Axiom 4
 - b) Axiom 7
 - c) Axiom 3
 - d) Axiom 5
 - e) Axiom 4

4.2
#16

$$H = \left\{ \begin{bmatrix} b-c \\ 2b+c+d \\ 5c-4d \\ d \end{bmatrix} : b, c, d \in \mathbb{R} \right\} = \left\{ \bar{x} : \bar{x} = b \begin{bmatrix} 1 \\ 2 \\ 0 \\ 0 \end{bmatrix} + c \begin{bmatrix} -1 \\ 1 \\ 5 \\ 0 \end{bmatrix} + d \begin{bmatrix} 0 \\ 1 \\ -4 \\ 1 \end{bmatrix}, b, c, d \in \mathbb{R} \right\}$$

So $H = \text{Col} \begin{bmatrix} 1 & -1 & 0 \\ 2 & 1 & 1 \\ 0 & 5 & -4 \\ 0 & 0 & 1 \end{bmatrix}$

4.2
#24

$\bar{w} \in \text{Col} A$ provided the system with augmented matrix $[A|\bar{w}]$ is consistent.

$$[A \ \bar{w}] = \begin{bmatrix} -8 & -2 & -9 & 2 \\ 6 & 4 & 8 & 1 \\ 4 & 0 & 4 & -2 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 & -1/2 \\ 0 & 0 & 1/2 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

So the system is consistent and $\bar{w} \in \text{Col} A$.

$$\begin{bmatrix} -8 & -2 & -9 \\ 6 & 4 & 8 \\ 4 & 0 & 4 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \bar{w} \in \text{Nul} A$$

4.2 / #26

- a) True, Thm 2
- b) True, Thm 3
- c) False, Col A is all \vec{b} such that the system is consistent.
- d) True, See p. 232 (below green box)
- e) True, See Fig 2
- f) True, See Example 8

4.2 / #32

Given $\vec{p} \in \mathbb{P}_2$, $\vec{p}(t) = a_0 + a_1 t + a_2 t^2$ for some $a_0, a_1, a_2 \in \mathbb{R}$
 So, for $\vec{p}(0) = 0$ we must have $a_0 = 0$. Hence,
 $\text{Ker } T = \{ \vec{p} \in \mathbb{P}_2 : \vec{p}(t) = a_1 t + a_2 t^2 \text{ for } a_1, a_2 \in \mathbb{R} \}$

So, $\text{Ker } T = \text{span} \{ t, t^2 \}$

$\text{Range } T = \{ \begin{bmatrix} a_0 \\ a_0 \end{bmatrix} : a_0 \in \mathbb{R} \}$

4.2 / #34

Let $\vec{f}, \vec{g} \in C[0,1]$ and $c \in \mathbb{R}$. Then $T(\vec{f}) = \vec{F}$ where $\vec{F}' = \vec{f}$ and $\vec{F}(0) = 0$ and $T(\vec{g}) = \vec{G}$ where $\vec{G}' = \vec{g}$ and $\vec{G}(0) = 0$. By the rules for anti-differentiation
 $(\vec{F} + \vec{G})' = \vec{f} + \vec{g}$ and $(\vec{F} + \vec{G})(0) = \vec{F}(0) + \vec{G}(0) = 0 + 0 = 0$
 and $(c\vec{F})' = c\vec{f}$ and $(c\vec{F})(0) = c\vec{F}(0) = c(0) = 0$.
 So, $T(\vec{f} + \vec{g}) = T(\vec{f}) + T(\vec{g})$ and $T(c\vec{f}) = cT(\vec{f})$
 and T is a linear transformation.

$\text{Ker } T = \{ \vec{f} \in C[0,1] : \delta \vec{f} = 0 \} = \{ \vec{0} \}$
 where $\vec{0}$ is the zero function.