

I. Definitions (3 points each). Write definitions of the specified terms. Be sure to use complete English sentences in all cases.

1. Define what it means for a set of indexed vectors $\{v_1, v_2, \dots, v_p\}$ to be *linearly independent*.

2. Define: *linear transformation*.

II Exercises (4 points each).

3. Suppose the matrix below is the augmented matrix for a linear system. Show, step-by-step, how to produce the unique reduced (row) echelon form of that matrix. State whether the associated linear system is consistent or inconsistent.

$$\left[\begin{array}{cccc} 3 & 6 & 6 & 9 \\ 1 & 2 & 3 & 10 \\ 1 & 2 & 4 & 0 \end{array} \right]$$

4. Suppose the matrix below is the reduced (row) echelon form for the augmented matrix of a linear system. Is the system consistent? Justify your response, and if you think the system is consistent specify either the unique solution or the general form for all solutions.

$$\begin{bmatrix} 1 & -2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 3 \\ 0 & 0 & 0 & 1 & -2 & -2 \end{bmatrix}$$

5. Suppose we define the 3×4 matrix A as below. Are the columns of A linearly independent? Justify your answer. If you think the columns form a linearly dependent set of vectors, write one column as a linear combination of the others.

$$A = \begin{bmatrix} 2 & -2 & 0 \\ 0 & 3 & -3 \\ 0 & 0 & 0 \end{bmatrix}$$

6. Suppose we define the 3×3 matrix B as below. Solve the homogeneous equation $B\mathbf{x} = \mathbf{0}$ and specify the general form of the solutions in parametric vector form.

$$B = \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

7. Is the transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ a linear transformation? Justify your answer by appealing directly to the definition of a linear transformation.

$$T([x_1, x_2]) = [2x_1 + 3x_2, |x_2|]$$

For example, $T([3, -4]) = [-6, 4]$

8. Given $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $T(\mathbf{v}) = A\mathbf{v}$ where A is the 2×2 matrix specified below, and suppose that \mathbf{b} is the 2×1 column vector defined below. Show how to find an \mathbf{x} in \mathbb{R}^2 such that $T(\mathbf{x}) = \mathbf{b}$. If no such \mathbf{x} exists, justify that response.

$$A = \begin{bmatrix} 2 & 4 \\ 0 & 3 \end{bmatrix}, \quad \mathbf{b} = \begin{bmatrix} 2 \\ 6 \end{bmatrix}$$

9. Is the mapping of Exercise #8 above onto \mathbb{R}^2 ? (Justify your answer.) Is the mapping of Exercise #8 above one-one? (Justify your answer.)