

Preview

- What is Pthreads
- The Thread ID
- The Thread Creation
- The thread Termination
- The pthread_join() function
- Mutex
- The pthread_cancel function
- The pthread_cleanup_push() function
- The pthread_cleanup_pop() function

What are Pthreads?

- Hardware vendors had implemented their own proprietary versions of threads.
- For a requirement of standardized programming interface, this interface has been specified by the IEEE POSIX 1003.1c standard (1995) (POSIX thread).
- Pthreads are defined as a set of C language programming types and procedure calls, implemented with a header file <pthread.h>

The Thread ID

- A Process ID (**pid_t**) for a process is unique in the system.
- But a thread ID (**pthread_t**) has significance only within the context of the process where it belongs.
- Even though unsigned long (Linux), unsigned integer (Solaris 9) is used represent a pthread_t, a function **pthread_equal()** must be used to compare thread ID.

The Thread ID

```
#include <pthread.h>

/*returns non-zero if equal, return 0 otherwise */
int pthread_equal(pthread_t t1, pthread_t t2);
```

```
#include <pthread.h>

/*returns thread ID of the calling thread */
pthread_t pthread_self(void);
```

The thread Creation

- Initially, your main() program comprises a single, default thread.
- All other threads must be explicitly created by the programmer
- **pthread_create()** function creates a new thread and makes it executable. This routine can be called any number of times from anywhere within your code.
- Once created, threads are peers, and may create other threads. **There is no implied hierarchy or dependency between threads**

The thread Creation

```
#include <pthread.h>
int pthread_create (pthread_t *thread,
                  const pthread_attr_t *att,
                  void *(*start_routine)(void*), void *arg);
```

- **att** point to structure of pthread attribute. If att is NULL, a default attribute will be used
- **start_routine** point to address of a void function with no parameter or
- We can save parameters to typeless pointer arg and be able to pass to the function.
- When multiple threads are created, there is **no guarantee which runs first.** It is depends on the thread scheduler.

The thread Creation

- On success, **pthread_create()** returns 0; on error, it returns an error number, and the contents of **thread* are undefined.
 - **EAGAIN** Insufficient resources to create another thread, or a system-imposed limit on the number of threads was encountered.
 - **EINVAL** Invalid settings in *attr*.
 - **EPERM** No permission to set the scheduling policy and parameters specified in *attr*.

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The thread Creation

- **pthread_attr_t**
 - int flags
 - int stacksize
 - int contentionscope
 - int inheritsched
 - int detachstate
 - int sched
 - struct sched_param param
 - struct timespec starttime deadline period

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Compile with pthread()

- To compile a program with pthread, we need provide pthread library to linker.

Ex)

Program file Name: example.c

Executable file name: example

Step 1) create object cord example.o

gcc -c example.c

Step 2) create an executable code example

gcc -pthread -o example example.o

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```

/*****
 createTh.c: Demonstrate creation of threads
 *****/
#include <stdio.h>
#include <stdlib.h>
#include <pthread.h>
#define NUM_THREADS 5

void *PrintHello(void *threadid)
{
    int tid;
    tid = (int)threadid;
    printf("Hello World! It's me, thread %d!\n", tid);
    pthread_exit(NULL);
}

int main(int argc, char *argv[])
{
    pthread_t threads[NUM_THREADS];
    int rc, t;
    for(t=0;t<NUM_THREADS;t++)
    {
        printf("In main: creating thread %d\n", t);
        rc = pthread_create(&threads[t], NULL, PrintHello, (void *)t);
        if (rc)
        {
            printf("ERROR: return code from pthread_create() is %d\n", rc);
            exit(-1);
        }
    }
    pthread_exit(NULL);
    exit (0);
}

```

```

/*****
 createTh2.c: Demonstrate creation of threads
 *****/
#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>
#define NUM_THREADS 5
static pthread_t getCurrentThreadId()
{
    return pthread_self();
}

// the function pointed by each thread by passing different parameter
void *PrintHello(void *threadid)
{
    int tid;
    tid = (int)threadid;
    pthread_t id = getCurrentThreadId(); //get a thread id
    printf("Hello World! It's me, thread %d! with thread id %d\n", tid, id);
    pthread_exit(NULL);
}

int main(int argc, char *argv[])
{
    pthread_t threads[NUM_THREADS];
    int rc, t;
    //create five threads pointing same function with different argument
    for(t=0;t<NUM_THREADS;t++)
    {
        printf("In main: creating thread %d\n", t);
        rc = pthread_create(&threads[t], NULL, PrintHello, (void *)t);
        if (rc!=0)
        {
            printf("ERROR: return code from pthread_create() is %d\n", rc);
            exit(1);
        }
    }
    pthread_exit(NULL);
    exit (0);
}

```

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```

/*****
 threadrace.c: Demonstrate race condition with multiple threads
 *****/
#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>
#define NUM_THREADS 5

int count =0;
void *printHi(void *) /* function prototype for threads function*/

int main(int argc, char *argv[])
{
    pthread_t threads[NUM_THREADS];
    int rc, t;
    for(t=0;t<NUM_THREADS;t++) /* create five threads */
    {
        printf("In main: creating thread %d\n", t);
        rc = pthread_create(&threads[t], NULL, printHi, (void *)t);
        if (rc!=0)
        {
            printf("ERROR: return code from pthread_create() is %d\n", rc);
            exit(1);
        }
    }
    pthread_exit(NULL);
    exit (0);
}

```

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```

void *printHi(void *threadid)
{
    int tid, i;

    tid = (int)threadid;

    if (tid % 2 == 0)
    {
        for (i = 0; i < 10; i++)
        {
            sleep(1);
            count++;
            printf("Hi!, thread %d! shared variable count = %d\n", tid, count);
        }
    }
    else
    {
        for (i = 0; i < 10; i++)
        {
            count++;
            sleep(1);
            printf("Hi!, thread %d! shared variable count = %d\n", tid, count);
        }
    }

    pthread_exit(NULL);
}

```

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The thread Termination

- If any thread within a process call `exit` or `_exit` system call, then the entire process terminate.
- A single thread inside a process can be terminated by three ways.
 - The thread can simply return from the start routine
 - The thread can be cancelled by another thread by calling `pthread_cancel()` function in the same process.
 - The thread can call `pthread_exit()` with some condition

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The thread Termination

```

#include <pthread>
void pthread_exit(void *rval_ptr);

```

- The `rval_ptr`: typeless pointer. This pointer is available to other threads in the process by calling the `pthread_join()` system call.

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Thread Synchronization

- Joining" is one way to accomplish synchronization between threads.
- There are three methods to synchronization between threads
 - Mutexes
 - Joining
 - Condition variables

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Mutexes

- A **Mutex** is a variable that can be in one of two state: unlock (0), lock(1).
- Modification to the value of a **Mutex** in the `unlock` and `lock` operations are executed indivisibly.
 - Lock operation check mutex value and if mutex =1, set mutex=0; if mutex = 0; sleep on the mutex queue
 - Unlock operation set mutex =1;
- **Mutexes** are used to prevent data inconsistencies due to race conditions
- **Mutexes** are used for serializing shared resources.
- If a global resource is accessed by several thread, the global resource should have a **Mutex** associated with it.

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Mutexes

- Scenario to avoid race condition without mutex (using variable lock)
 - Each thread need check lock variable before entering a critical region.
 - If lock =0 then a thread can enter to a critical region.
 - If lock = 1 then other thread cannot enter the critical region.
 - Once a thread finish its job in the critical region, set lock = 0 and let other thread enter the critical region.

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Mutexes

```
repeat
while lock ≠ 0 do
; (no-operation)
lock = 1
Critical Section
lock = 0;
Remainder Section
until false
```

Scenario)

- Initially lock = 0.
- A process (or thread) P_1 tries get into critical section. A process check lock value = 0.
- Process P_1 CPU time is over and go to ready state, before updating lock = 1.
- Process P_2 tries get into critical section. P_2 check lock value lock = 0
- P_2 set lock = 1 and go to critical section.
- P_1 CPU time is over and P_1 is rescheduled.
- P_1 already read lock = 0, P_2 set lock = 1 and go to Critical section. Now P_1 and P_2 are in the critical section at the same time

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Mutexes

```
pthread_mutex_t mutex1 = PTHREAD_MUTEX_INITIALIZER
repeat
pthread_mutex_lock( &mutex1 );
Critical Section
pthread_mutex_unlock( &mutex1 );
Remainder Section
until false
```

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```
.....
threadrace.c: Demonstrate race condition with multiple threads
.....
#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>
#define NUM_THREADS 5

int count =0; /* global variable shared by multiple threads*/
void *printHi(void *); /* function prototype for threads function*/

int main(int argc, char *argv[])
{
pthread_t threads[NUM_THREADS];
int rc, t;
for(t=0;t<NUM_THREADS;t++) /* create five threads */
{
printf("In main: creating thread %d\n", t);
rc = pthread_create(&threads[t], NULL, printHi, (void *)t);
if (rc!=0)
{
printf("ERROR: return code from pthread_create() is %d\n", rc);
exit(1);
}
}
pthread_exit(NULL);
exit(0);
}
```

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```
void *printHi(void *threadid)
{
int tid, i;

tid = (int)threadid;

if (tid % 2 == 0) /* for a thread with even number*/
{
for (i =0; i<10; i++)
{
sleep(1);
count++;
printf("Hi!, thread #!d! shared variable count = %d\n", tid, count);
}
}
else /* for a thread with odd number*/
{
for (i =0; i<10; i++)
{
count++;
sleep(1);
printf("Hi!, thread #!d! shared variable count = %d\n", tid, count);
}
}

pthread_exit(NULL);
}
```

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```
.....
threadrace1.c:
Demonstrate to use mutex to avoid race condition between multiple threads
.....
#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>
#define NUM_THREADS 5
/* mutex for shared variable count is initiated*/
pthread_mutex_t count_mutex = PTHREAD_MUTEX_INITIALIZER;
int count =0; /* shared variable between threads */
void *printHi(void *);
int main(int argc, char *argv[])
{
pthread_t threads[NUM_THREADS];
int rc, t;
for(t=0;t<NUM_THREADS;t++)
{
printf("In main: creating thread %d\n", t);
rc = pthread_create(&threads[t], NULL, printHi, (void *)t);
if (rc!=0)
{
printf("ERROR: return code from pthread_create() is %d\n", rc);
exit(1);
}
}
pthread_exit(NULL);
exit(0);
}
```

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```
void *printHi(void *threadid)
{
int tid, i;

tid = (int)threadid;

if (tid % 2 == 0) /* for a thread with even number*/
{
for (i =0; i<10; i++)
{
pthread_mutex_lock(&count_mutex);
sleep(1);
count++;
printf("Hi!, thread #!d! shared variable count = %d\n", tid, count);
pthread_mutex_unlock(&count_mutex);
}
}
else /* for a thread with odd number*/
{
for (i =0; i<10; i++)
{
pthread_mutex_lock(&count_mutex);
count++;
sleep(1);
printf("Hi!, thread #!d! shared variable count = %d\n", tid, count);
pthread_mutex_unlock(&count_mutex);
}
}

pthread_exit(NULL);
}
```

The pthread_join()

```
#include <pthread.h>
```

```
int pthread_join(pthread_t thread, void **value_ptr);
```

- The `pthread_join()` function suspends execution of the calling thread until the target thread terminates, unless the target thread has already terminated.
- The typeless pointer `**value_ptr` can be used to pass more than a single value (used as return value from the function).
 - Return 0 if no error
 - Return error number on failure
 - EINVAL – not joinable thread
 - ESRCH – no such a thread
 - EDEADLK – dead lock

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```
/*thJoin.c demonstrate two thread without pthread_join() function */
#include <pthread.h>
#include <stdio.h>

void *thrd_f1(void *); /* for thread 1 */
void * thrd_f2(void *); /* for thread 2 */
void err_sys(char *, int); /* error function */

int main()
{
    int rc;
    pthread_t tid1, tid2;
    void *tret;

    /* create the first thread */
    printf("About to create the first thread\n");
    if ((rc=pthread_create(&tid1, NULL, thrd_f1, NULL)) != 0)
        err_sys("ERROR: return code from pthread_create() is", rc);
    /* create second thread */
    printf("About to create the second thread\n");
    if ((rc=pthread_create(&tid2, NULL, thrd_f2, NULL)) != 0)
        err_sys("ERROR: return code from pthread_create() is", rc);

    exit(0);
}
```

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The pthread_join()

```
/* for thread 1 */
void *thrd_f1(void *arg)
{
    sleep(5);
    printf("Thread 1 is about to finish \n");
    return ((void *) 1);
}

/* for thread 2 */
void * thrd_f2(void *arg)
{
    sleep(5);
    printf("Thread 2 is about to finish \n");
    return ((void *) 2);
}

void err_sys(char *str, int msg)
{
    printf ("\"%s %d\n\",str, msg);
    exit (1);
}
```

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```
/*thJoin.c: demonstrate pthread_join() function */
#include <pthread.h>
#include <stdio.h>

void *thrd_f1(void *); /* for thread 1 */
void *thrd_f2(void *); /* for thread 2 */
void err_sys(char *, int); /* error function */

int main()
{
    int rc;
    pthread_t tid1, tid2;
    void *tret1, *tret2;

    /* create the first thread */
    if ((rc=pthread_create(&tid1, NULL, thrd_f1, NULL)) != 0)
        err_sys("ERROR: return code from pthread_create() is", rc);
    /* create second thread */
    if ((rc=pthread_create(&tid2, NULL, thrd_f2, NULL)) != 0)
        err_sys("ERROR: return code from pthread_create() is", rc);
    /* waiting for first thread finish */
    if ((rc =pthread_join(tid1, &tret1)) != 0)
        err_sys("ERROR: return code from pthread_join() is", rc);

    printf("Thread 1 exit code %d\n", (int)tret1);
    /*waiting for second thread finish */
    if ((rc =pthread_join(tid2, &tret2)) != 0)
        err_sys("ERROR: return code from pthread_join() is", rc);
    printf("Thread 2 exit code %d\n", (int)tret2);
    exit(0);
}
```

The pthread_join()

```
/* for thread 1 */
void *thrd_f1(void *arg)
{
    sleep(1);
    printf("Thread 1 is about to finish \n");
    return ((void *) 1);
}

/* for thread 2 */
void * thrd_f2(void *arg)
{
    sleep(1);
    printf("Thread 2 is about to finish \n");
    return ((void *) 2);
}

void err_sys(char *str, int msg)
{
    printf ("\"%s %d\n\",str, msg);
    exit (1);
}
```

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```
/* thJoin.c: demonstrate without pthread_join() function */
#include <stdio.h>
#include <pthread.h>
#define NTHREADS 10

void *thread_function(void *)
void err_sys(char *, int);
/*mutex for mutual exclusion */
pthread_mutex_t mutex1 = PTHREAD_MUTEX_INITIALIZER;
int counter = 0;

void main()
{
    pthread_t thread_id[NTHREADS];
    int i, j, rc;
    for(i=0; i < NTHREADS; i++)
        if ((rc =pthread_create(&thread_id[i], NULL, thread_function, (void *)i)) != 0)
            err_sys("ERROR: return code from pthread_create() is", rc);

    /* Since pthread_join() was not called for each thread, program might terminate before */
    /* each thread's completion */
    printf("Final counter value: %d\n", counter);
    exit (0);
}

void *thread_function(void *)
{
    int tnum = (int)i;
    printf("Thread number %d, id = %d\n", tnum, pthread_self());
    pthread_mutex_lock(&mutex1);
    counter++;
    pthread_mutex_unlock(&mutex1);
}

void err_sys(char *str, int msg)
{
    printf ("\"%s %d\n\",str, msg);
    exit (1);
}
```

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```

/* thjoin1.c: demonstrate pthread_join() function */
/* synchronizing sequence of thread's job */
#include <stdio.h>
#include <pthread.h>
#define NTHREADS 10

void *thread_function(void *)
void err_sys(char *, int);
/*mutex for mutual exclusion */
pthread_mutex_t mutex1 = PTHREAD_MUTEX_INITIALIZER;
int counter = 0;

void main()
{
    pthread_t thread_id[NTHREADS];
    int i, j, rc;
    for(i=0; i < NTHREADS; i++)
        if ((rc = pthread_create( &thread_id[i], NULL, thread_function, (void *) i )) != 0)
            err_sys("ERROR: return code from pthread_create() is", rc);
    for(j=0; j < NTHREADS; j++)
        if ((rc = pthread_join( thread_id[j], NULL)) != 0)
            err_sys("ERROR: return code from pthread_join() is", rc);

    /* Now that all threads are complete I can print the final result. */
    /* Without the join I could be printing a value before all the threads */
    /* have been completed. */
    printf("Final counter value: %d\n", counter);
    exit(0);
}

void *thread_function(void *)
{
    int tnum = (int)i;
    printf("Thread number %d ID = %d\n", pthread_self());
    pthread_mutex_lock( &mutex1 );
    counter++;
    pthread_mutex_unlock( &mutex1 );
}

void err_sys(char *str, int msg)
{
    printf (" %s %d\n",str, msg);
    exit(1);
}
    
```

```

/* thjoin1.c: demonstrate pthread_join() function */
/* synchronizing sequence of thread's job. Considered mutual exclusion with mutex. */
#include <stdio.h>
#include <pthread.h>
#define NTHREADS 10

void *thread_function(void *)
void err_sys(char *, int);
/*mutex for mutual exclusion */
pthread_mutex_t mutex1 = PTHREAD_MUTEX_INITIALIZER;
int counter = 0;

void main()
{
    pthread_t thread_id[NTHREADS];
    int i, j, rc;
    for(i=0; i < NTHREADS; i++)
        if ((rc = pthread_create( &thread_id[i], NULL, thread_function, (void *) i )) != 0)
            err_sys("ERROR: return code from pthread_create() is", rc);
    for(j=0; j < NTHREADS; j++)
        if ((rc = pthread_join( thread_id[j], NULL)) != 0)
            err_sys("ERROR: return code from pthread_join() is", rc);

    /* Now that all threads are complete I can print the final result. */
    /* Without the join I could be printing a value before all the threads */
    /* have been completed. */
    printf("Final counter value: %d\n", counter);
    exit(0);
}

void *thread_function(void *)
{
    int i;
    int tnum=(int)i;
    for (i=1; i <= 10; i++)
    {
        printf("Thread number %d ID = %d\n",i,tnum, pthread_self());
        sleep(1);
        pthread_mutex_lock( &mutex1 );
        counter++;
        pthread_mutex_unlock( &mutex1 );
    }
}

void err_sys(char *str, int msg)
{
    printf (" %s %d\n",str, msg);
    exit(1);
}
    
```

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```

/* thjoin1.c: demonstrate pthread_join() function */
/* synchronizing sequence of thread's job. no mutual exclusion */
#include <stdio.h>
#include <pthread.h>
#define NTHREADS 10

void *thread_function(void *)
void err_sys(char *, int);
int counter = 0;

void main()
{
    pthread_t thread_id[NTHREADS];
    int i, j, rc;
    for(i=0; i < NTHREADS; i++)
        if ((rc = pthread_create( &thread_id[i], NULL, thread_function, (void *) i )) != 0)
            err_sys("ERROR: return code from pthread_create() is", rc);
    for(j=0; j < NTHREADS; j++)
        if ((rc = pthread_join( thread_id[j], NULL)) != 0)
            err_sys("ERROR: return code from pthread_join() is", rc);

    /* Now that all threads are complete I can print the final result. */
    /* Without the join I could be printing a value before all the threads */
    /* have been completed. */
    printf("Final counter value: %d\n", counter);
    exit(0);
}

void *thread_function(void *)
{
    int i, tnum = (int)i;
    for (i=1; i <= 10; i++)
    {
        printf("Thread number %d, %d\n", tnum, pthread_self());
        sleep(1);
        counter++;
    }
}

void err_sys(char *str, int msg)
{
    printf (" %s %d\n",str, msg);
    exit(1);
}
    
```

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```

/* thjoin2.c: demonstrate pthread_join() function */
/* synchronizing sequence of thread's job */
#include <stdio.h>
#include <pthread.h>
#define NTHREADS 100

void *thread_function(void *)
void err_sys(char *, int);
/*mutex for mutual exclusion */
pthread_mutex_t mutex1 = PTHREAD_MUTEX_INITIALIZER;
int counter = 0;

void main()
{
    pthread_t thread_id[NTHREADS];
    int i, j, rc;
    for(i=0; i < NTHREADS; i++)
        if ((rc = pthread_create( &thread_id[i], NULL, thread_function, (void *) i )) != 0)
            err_sys("ERROR: return code from pthread_create() is", rc);
    for(j=0; j < NTHREADS; j++)
        if ((rc = pthread_join( thread_id[j], NULL)) != 0)
            err_sys("ERROR: return code from pthread_join() is", rc);

    /* Now that all threads are complete I can print the final result. */
    /* Without the join I could be printing a value before all the threads */
    /* have been completed. */
    printf("Final counter value: %d\n", counter);
    exit(0);
}

void *thread_function(void *arg)
{
    int x = (int) (void *) arg;
    pthread_mutex_lock( &mutex1 );
    counter++;
    printf("Thread number %d: counter = %d\n", x, counter);
    pthread_mutex_unlock( &mutex1 );
}

void err_sys(char *str, int msg)
{
    printf (" %s %d\n",str, msg);
    exit(1);
}
    
```

```

/* thjoin1.c: demonstrate pthread_join() function */
/* synchronizing sequence of thread's job */
#include <stdio.h>
#include <pthread.h>
#define NTHREADS 100

void *thread_function(void *)
void err_sys(char *, int);
int counter = 0;

void main()
{
    pthread_t thread_id[NTHREADS];
    int i, j, rc;
    for(i=0; i < NTHREADS; i++)
        if ((rc = pthread_create( &thread_id[i], NULL, thread_function, (void *) i )) != 0)
            err_sys("ERROR: return code from pthread_create() is", rc);
    for(j=0; j < NTHREADS; j++)
        if ((rc = pthread_join( thread_id[j], NULL)) != 0)
            err_sys("ERROR: return code from pthread_join() is", rc);

    /* Now that all threads are complete I can print the final result. */
    /* Without the join I could be printing a value before all the threads */
    /* have been completed. */
    printf("Final counter value: %d\n", counter);
    exit(0);
}

void *thread_function(void *arg)
{
    int x = (int) (void *) arg;
    /* Now counter does not protected mutual exclusion. */
    counter++;
    printf("Thread number %d: counter = %d\n", x, counter);
}

void err_sys(char *str, int msg)
{
    printf (" %s %d\n",str, msg);
    exit(1);
}
    
```

```

/* thjoin1.c: demonstrate without pthread_join() function */
/* synchronizing sequence of thread's job */
#include <stdio.h>
#include <pthread.h>
#define NTHREADS 100

void *thread_function(void *)
void err_sys(char *, int);
/*mutex for mutual exclusion */
pthread_mutex_t mutex1 = PTHREAD_MUTEX_INITIALIZER;
int counter = 0;

void main()
{
    pthread_t thread_id[NTHREADS];
    int i, j, rc;
    for(i=0; i < NTHREADS; i++)
        if ((rc = pthread_create( &thread_id[i], NULL, thread_function, (void *) i )) != 0)
            err_sys("ERROR: return code from pthread_create() is", rc);

    /* Without the join I could print a value before all the threads */
    /* have been completed. */
    printf("Final counter value: %d\n", counter);
    exit(0);
}

void *thread_function(void *arg)
{
    int x = (int) (void *) arg;
    printf("Thread number %d\n", x);
    pthread_mutex_lock( &mutex1 );
    counter++;
    pthread_mutex_unlock( &mutex1 );
}

void err_sys(char *str, int msg)
{
    printf (" %s %d\n",str, msg);
    exit(1);
}
    
```

The pthread_cancel()

- The **pthread_cancel()** function requests cancellation of the target thread.
- The target thread is cancelled, based on its ability to be cancelled.
- When cancel ability is deferred, all cancels are held pending in the target thread until the thread changes the cancel ability, calls a function that is a cancellation point.

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The pthread_cancel()

- Cancellation points:
 - pthread_cond_timedwait()
 - pthread_cond_wait()
 - pthread_delay_np()
 - pthread_join()
 - pthread_join_np()
 - pthread_extendedjoin_np()
 - pthread_testcancel()

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```

/* thcancel.c: demonstrate pthread_cancel() function */
#include <pthread.h>
#include <stdio.h>

void *threadfunc(void *)
void err_sys(char *, int );

int main(int argc, char **argv)
{
    pthread_t tid;
    int rc;

    printf("Entering testcase\n");
    /* create a thread */
    if ((rc = pthread_create(&tid, NULL, threadfunc, NULL)) != 0)
        err_sys("ERROR: return code from pthread_create() is", rc);
    sleep(2);
    printf("Now Canceling the thread\n");
    /* try to cancel the thread created */
    if ((rc = pthread_cancel(tid)) != 0)
        err_sys("ERROR: return code from pthread_cancel() is", rc);
    if ((rc = pthread_join(tid, NULL)) != 0)
        err_sys("ERROR: return code from pthread_join() is", rc);
    sleep(3);
    printf("Main completed\n");
    return 0;
}

void err_sys(char *str, int msg)
{
    printf("%s %d\n", str, msg);
    exit(1);
}

void *threadfunc(void *parm)
{
    printf("Entered secondary thread\n");
    while (1)
    {
        printf("Secondary thread is looping\n");
        pthread_testcancel(); /* cancel point */
        sleep(1);
    }
}

```

The pthread_cleanup_push()

```

#include <pthread.h>
void pthread_cleanup_push(void (*routine)(void *), void *arg);

```

- The **pthread_cleanup_push()** function pushes a clean up function routine, to be called with the single argument, arg, when the thread performs one of the following actions.
 - pthread_exit()
 - pthread_cancel()

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The pthread_cleanup_pop()

```

#include <pthread.h>
void pthread_cleanup_pop(int execute);

```

- The **pthread_cleanup_pop()** function pops the last cleanup handler from the cancellation cleanup stack.
- If the *execute* parameter is nonzero, the handler is called with the argument specified by the **pthread_cleanup_push()** call with which the handler was registered.

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```

/* thpushpop.c: demonstrate
pthread_cleanup_push() and pthread_cleanup_pop() */
#include <pthread.h>
#include <stdio.h>
void err_sys(char *, int );
void cleanuphandler(void *);
void *threadfunc(void *);

int main()
{
    pthread_t tid;
    int rc=0;

    printf("Entering testcase\n");
    /* now creating a thread */
    if ((rc = pthread_create(&tid, NULL, threadfunc, NULL)) != 0)
        err_sys("ERROR: return code from pthread_create() is", rc);
    sleep(2);

    printf("Now Canceling the thread\n");
    /* now cancelling the created thread */
    if ((rc = pthread_cancel(tid)) != 0)
        err_sys("ERROR: return code from pthread_cancel() is", rc);
    sleep(3);
    if ((rc = pthread_join(tid, NULL)) != 0)
        err_sys("ERROR: return code from pthread_join() is", rc);
    printf("Main completed\n");
    return 0;
}

```

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The `pthread_cleanup_pop()`

```
void err_exit(char *str, int msg)
{
    printf ("%s %d\n",str, msg);
    exit (1);
}

void cleanupHandler(void *arg)
{
    printf("Master ask me terminate myself!\n");
    sleep(2);
    printf("I will be back!\n");
}

void *threadfunc(void *parm)
{
    printf("Entered secondary thread\n");
    /* push cleanup function after cancel */
    pthread_cleanup_push(cleanupHandler, NULL);
    while (1) {
        printf("Master! Don't terminate me! I want live forever!\n");
        pthread_testcancel(); /* cancel point */
        sleep(1);
    }
    pthread_cleanup_pop(0);
    return NULL;
}
```