

## 1. (1 pt)

- Running state – a process is running on CPU.
- Ready state – a process waiting for CPU (short term scheduler will assign CPU for it)
- Blocked state – a process waiting for some I/O (signal, child termination, input from keyboard ..)
- Transaction 1 – a process is suspended since it need some I/O
- Transaction 2 – a process used up it's time quantum (time out)
- Transaction 3 – since CPU become available, CPU scheduler select a process from ready queue and let it use CPU
- Transaction 4 –some I/O become available; a process ready to be selected by scheduler

## 2. (3 pt.)

```

/* task2.c: demonstrate waitpid system call */
#include <stdio.h>
#include <unistd.h>
#include <sys/wait.h>
#include <stdlib.h>
int main()
{
    pid_t pid, pid1, ppid;
    int i, endID, status;

    pid = fork(); /*create the first child */
    if (pid == 0) /* code for first child */
    {
        //create a grand child by the first child
        pid1 = fork();
        if (pid1 >0)
        {
            for (i=0; i<100; i++)
            {
                printf("I am your child with ID = %d \n", getpid());
                sleep(1);
            }
            _exit(0);
        }
        else
        {
            ppid = getppid();
            while (1)
            {
                if (getppid()==ppid)
                {
                    printf("I am your grandchild \n");
                    sleep(1);
                }
                else
                    _exit(0);
            }
        }
    }
    else
    {
        while (1)
        {
            endID=waitpid(pid, &status, WNOHANG|WUNTRACED);
            if (endID==0) //child still running
            {
                printf("I am your parent with ID= %d\n",getpid());
                sleep(1);
            }
            else
            {
                printf("Now my job is over \n");
                exit(0);
            }
        }
    }
}

```

## 3. (2 pt.)

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>

int main (int argc, char *argv[])
{
    int i,n,m ;
    char * buffer, ch[20];

    i=atoi(argv[1]);

    buffer = (char*) malloc (i+1);
    if (buffer==NULL)
        exit (1);

    for (n=0; n<i; n++)
        buffer[n]=rand()%26+'a';
    buffer[i]='\0';
    printf ("Random string: %s\n",buffer);

    write (1,"integer for extension?", 22);
    read(0, ch, 20);
    m=atoi(ch);
    buffer = (char*) realloc(buffer, (i+m)*sizeof (char));

    for (n = i; n< i+m; n++)
        buffer[n]=rand()%26+'a';
    buffer[i+m]='\0';
    printf ("Extended Random string: %s\n", buffer);

    free (buffer);

    return 0;
}
```

4.

- a. (0.5 pt.) What is Race condition? –A situation where two or more processes are reading or writing some shared data and the final result depends on who runs precisely when.
- b. (0.5 pt.) What is mutual exclusion of critical section – only one process can access shared resources at any moment.
- c. (0.5 pt.) What is Zombie process – when a child process terminate if parent does not call wait() or waitpid() to get child process's termination status, child will be remain as a zombie.
- d. (0.5 pt.) A process can create a child process by using fork() or vfork() system call. Discuss two main differences between two child created by fork() and vfork().

A child with fork(): has it's own address space. Only share text segment with its parent.

A child with vfork(): memory space is shared with its parent. A parent always wait for the child.

5. (2 pt.)

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>

int main(void)
{
    int pid;
    pid=fork();
    if(pid>0)
        while (1);
    else
    {
        pid =fork();
        if (pid >0)
            exit(0);
        else
            while(1);
    }
}
```