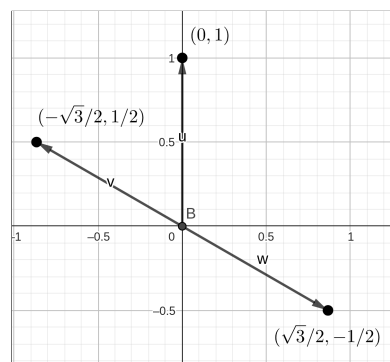
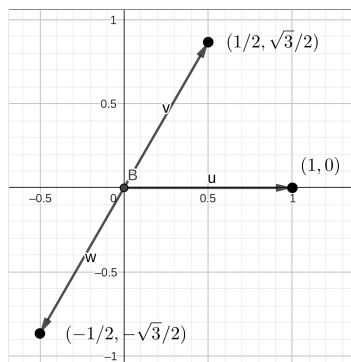


1. (30 points): Mark each of the following as either True or False by circling the correct answer.
- (a) **True** **False:** If A is an $m \times n$ matrix, then the range of the transformation $\mathbf{x} \rightarrow A\mathbf{x}$ is \mathbb{R}^m . **Solution:** False
 - (b) **True** **False:** Every linear transformation is a matrix transformation. **Solution:** False
 - (c) **True** **False:** When two linear transformations are performed one after another, the combined effect may not always be a linear transformation. **Solution:** False
 - (d) **True** **False:** A linear transformation $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is completely determined by its effect on the columns of the $n \times n$ identity matrix. **Solution:** True
 - (e) **True** **False:** $AB + AC = A(B + C)$ **Solution:** True
 - (f) **True** **False:** Each column of AB is a linear combination of the columns of B using weights from the corresponding column of A . **Solution:** False
 - (g) **True** **False:** If A is an invertible $n \times n$ matrix, then the equation $A\mathbf{x} = \mathbf{b}$ is consistent for *each* \mathbf{b} in \mathbb{R}^n . **Solution:** True
 - (h) **True** **False:** Each elementary matrix is invertible. **Solution:** True
 - (i) **True** **False:** If A is an $n \times n$ matrix and the columns of A span \mathbb{R}^n , then the columns of A are linearly independent. **Solution:** True
 - (j) **True** **False:** If A^T is not invertible, then A is not invertible. **Solution:** True

2. (15 points): Find the matrix of the transformation from \mathbb{R}^2 to \mathbb{R}^2 that rotates all the vectors counterclockwise by an angle of $\theta = \frac{\pi}{3}$ and then reflects the vector through the origin. Keep your answer in exact form.

Solution: $A = [T(\mathbf{e}_1) \ T(\mathbf{e}_2)]$. Start with $\mathbf{e}_1 = (1, 0)$ the rotation takes the point to $(1/2, \sqrt{3}/2)$ then the reflection takes that to $(-1/2, -\sqrt{3}/2)$ which is the first column of A . Now $\mathbf{e}_2 = (0, 1)$ the rotation takes the point to $(-\sqrt{3}/2, 1/2)$ then the reflection takes that to $(\sqrt{3}/2, -1/2)$ which is the second column of A .



So the transformation matrix is, $A = \begin{bmatrix} -1/2 & \sqrt{3}/2 \\ -\sqrt{3}/2 & -1/2 \end{bmatrix}$

Solution: Another way to do this is the rotation counterclockwise by an angle θ is

$$R_\theta = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix}$$

So rotation by $\theta = \frac{\pi}{3}$ is

$$R_{\pi/3} = \begin{bmatrix} 1/2 & -\sqrt{3}/2 \\ \sqrt{3}/2 & 1/2 \end{bmatrix}$$

Reflection through the origin has matrix,

$$R_{\mathcal{O}} = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}$$

So the transformation matrix we desire is $R_{\mathcal{O}}R_{\pi/3}$ which is,

$$A = \begin{bmatrix} -1/2 & \sqrt{3}/2 \\ -\sqrt{3}/2 & -1/2 \end{bmatrix}$$

3. (15 points): Let A and B be as follows, compute AB and BA . If the computation is undefined state why.

$$A = \begin{bmatrix} 1 & 2 & -3 \\ 3 & 7 & 5 \end{bmatrix} \quad B = \begin{bmatrix} 4 & -3 & 2 \\ 1 & -1 & 1 \\ 2 & 5 & -3 \end{bmatrix}$$

Solution:

$$AB = \begin{bmatrix} 0 & -20 & 13 \\ 29 & 9 & -2 \end{bmatrix}$$

BA does not exist since the number of columns of B is not the same as the number of rows of A .

4. (20 points): Find the inverse of the following matrix if it exists. If it does not exist, state why.

$$A = \begin{bmatrix} 8 & 3 & 1 \\ -17 & -7 & -2 \\ 10 & 4 & 1 \end{bmatrix}$$

Solution:

$$\begin{bmatrix} 8 & 3 & 1 & 1 & 0 & 0 \\ -17 & -7 & -2 & 0 & 1 & 0 \\ 10 & 4 & 1 & 0 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 1 & 1 & 1 \\ 0 & 1 & 0 & -3 & -2 & -1 \\ 0 & 0 & 1 & 2 & -2 & -5 \end{bmatrix}$$

so the inverse is

$$\begin{bmatrix} 1 & 1 & 1 \\ -3 & -2 & -1 \\ 2 & -2 & -5 \end{bmatrix}$$

5. (20 points): Find the LU decomposition of the matrix,

$$A = \begin{bmatrix} 2 & -1 & 2 \\ -6 & 0 & -2 \\ 8 & -1 & 5 \end{bmatrix}$$

Solution:

$$L = \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 4 & -1 & 1 \end{bmatrix} \quad U = \begin{bmatrix} 2 & -1 & 2 \\ 0 & -3 & 4 \\ 0 & 0 & 1 \end{bmatrix}$$

6. **Extra Credit:** (10 points): Suppose A is an $n \times n$ matrix and the equation $A\mathbf{x} = \mathbf{0}$

has only the trivial solution. Let $\mathbf{b} = \begin{bmatrix} 1 \\ 2 \\ \vdots \\ n \end{bmatrix}$ show that $A\mathbf{x} = \mathbf{b}$ has a solution.

Solution: If $A\mathbf{x} = \mathbf{0}$ has only the trivial solution then A is an invertible matrix, hence the equation $A\mathbf{x} = \mathbf{b}$ has a solution for all $\mathbf{b} \in \mathbb{R}^n$, specifically, $\mathbf{x} = A^{-1}\mathbf{b}$.