MATH 306 Exam III (3.1 - 4.7) Review

- 1. Know the definition of determinant and how to find the determinant of a matrix.
- 2. Know the properties of the determinant and how to apply Cramer's rule to find the unique solution of the matrix equation $A\mathbf{x} = \mathbf{b}$.
- 3. Know the definition of vector spaces and subspaces and be able to determine if a given set with two operations defined is a vector space or subspace.
- 4. Know how to find a basis for the null space, row space, column space and left null space of a given matrix A.
- 5. Know how to determine if a set is linearly independent and if a set is a basis for a vector space.
- 6. Know how to find the dimension of a vector space.
- 7. Know the criteria for a transformation to be a linear transformation and what the kernel and range of a transformation are.

A Few Questions & Worked Examples

1. Determine the values of the parameter s for which the system has a unique solution, and describe the solution.

$$6sx_1 + 4x_2 = 5
9x_1 + 2sx_2 = -2$$

2. Given the matrix

$$\left[
\begin{array}{ccc}
1 & a & a^2 \\
1 & b & b^2 \\
1 & c & c^2
\end{array}
\right]$$

Use row operations to show that det T = (b-a)(c-a)(c-b).

$$\det \mathbf{T} = \begin{vmatrix} 1 & a & a^2 \\ 1 & b & b^2 \\ 1 & c & c^2 \end{vmatrix} = \begin{vmatrix} 1 & a & a^2 \\ 0 & b - a & b^2 - a^2 \\ 0 & c - a & c^2 - a^2 \end{vmatrix} = \begin{vmatrix} 1 & a & a^2 \\ 0 & b - a & (b - a)(b + a) \\ 0 & c - a & (c - a)(c + a) \end{vmatrix}$$

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$$= (b-a)(c-a) \begin{vmatrix} 1 & a & a^2 \\ 0 & 1 & (b+a) \\ 0 & 1 & (c+a) \end{vmatrix} = (b-a)(c-a) \begin{vmatrix} 1 & a & a^2 \\ 0 & 1 & (b+a) \\ 0 & 0 & (c-b) \end{vmatrix} = (b-a)(c-a)(c-b)$$

3. Suppose that $\mathbb{R}^4 = \text{Span } \{v_1, \dots, v_4\}$. Explain why $\{v_1, \dots, v_4\}$ is a basis for \mathbb{R}^4 .

Let $A = [\mathbf{v_1} \ \mathbf{v_2} \ \mathbf{v_3} \ \mathbf{v_4}]$. Then A is square and its columns span \mathbb{R}^4 since $\mathbb{R}^4 = \operatorname{Span} \{\mathbf{v_1}, \dots, \mathbf{v_4}\}$ So its columns are linearly independent by the Invertible Matrix Theorem, and $\{\mathbf{v_1}, \mathbf{v_2}, \mathbf{v_3}, \mathbf{v_4}\}$ is a basis for \mathbb{R}^4 .

4. Use coordinate vectors to test the linear independence of the following set of polynomials.

$$(t-1)^2, t^3-2, (t-2)^3$$

Example exercises: Quiz & Homework questions;

Ch.3 Supplementary Exercises, #1 - 17;

Ch.4 Supplementary Exercises, #1 - 17.